

# Information Compressed and Transmitted and Reconstructed System of CGH with LOCO-I Image Processing and Fraunhofer Transforming Technique

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In this paper, the information compressed and transmitted and reconstructed software system (ICTRS) of Computer generated hologram (CGH) has been designed and established which can be widely applied by computer operators. This system structure can be applied to resolve the remote signal processing using the digital filter of CGH. It is a new system structure, and the size of image displayed is bigger (i.e.,  $7.11 \times 7.11(\text{inch}^2)$ ). In this system, LOCO-I image encoding technique and the image reconstruction technique using Fraunhofer transforming algorithm have been adapted. This processing method is a "lossless" or "near-lossless" compression algorithm whose compression ratio can be achieved to 1 : 5 (i.e., the compression ratio is 18.7806%), and the image of processed CGH can be effectively reconstructed by a computer. In experiments, we have mainly discussed and analyzed the amplitude and phase variation of CGH's pixels. In detail, we have explained why the image quality of processed CGH can be influenced by the pixel's amplitude and phase varied. The image quality of processed CGH has been compared with the image quality of original CGH, and the reconstructed image quality of processed CGH has been compared with the reconstructed image quality of original CGH in ICTRS. Finally, Compression ratio (R), Mean squared error (MSE) and Pear signal to noise ratio (PSNR) have been precisely calculated and analyzed to evaluate the reconstructed images quality of processed CGH and the image quality of processed CGH. The better compression and transmission and reconstruction algorithm model of CGH can be determined by the distortion measure. In this system, the image quality of processed CGH has been relatively improved. This method of processing CGH has been effectively verified by experiments.

**Keywords:** ICTRS, CGH, LOCO-I, Fraunhofer transforming technique, compressed and transmitted and reconstructed.

## 1. Introduction

In this paper, the information compressed and transmitted and reconstructed software system of CGH has been designed and established as shown in Fig.1. It can be applied in the remote signal processing using the digital filter of CGH. In this system, LOCO-I (Low Complexity Lossless Compression for Images) image processing algorithm model <sup>(2)~(4)</sup> and Fraunhofer transforming technique <sup>(6)~(9)</sup> have been adapted to process CGH. This method of processing CGH is different from JPEG baseline image processing and Fresnel transforming technique <sup>(1)</sup>. It is the "lossless" or "near-lossless" compression and transmission technique. The diffraction-pattern calculation can be further simplified and the restrictions can be more stringent than those used in the Fresnel approximations are adapted. Using this system, a few problems have been discussed when CGH are compressed and transmitted and reconstructed.

In researching, some documents about CGH processed have been investigated. Their processing methods are about the electronic hologram hardware display system <sup>(11)~(13)</sup>. However, at present the computer

has quickly been developed and widely been applied in the every field, and CGH has the potential application. Thus we think whether we should use the computer software to complete the total process of CGH compressed and transmitted and reconstructed.

The aim of processing CGH is that the information content of CGH is compressed and quickly transmitted in electronic system (e.g., the Internet). Therefore, if the algorithm model exists the error problems to process CGH, the image of CGH could not be effectively reconstructed after compression and transmission. So it is very important that a suitable compression algorithm model is chosen for CGH. Moreover the image processing theories have told us, the image compressed is to remove the redundancy information of image. The redundancy of processed CGH is the interpixel redundancy and the coding redundancy. Thus we must choice a suitable encoding algorithm to resolve these problems.

It is well known that CGH is a collection of special optical element. During the processing, if the lost information of CGH exceeds certain limit value, its original information distribution (i.e., the amplitude and phase functions) will be varied. In terms of the De-tour phase holograms principle of B. R. Brown and A.

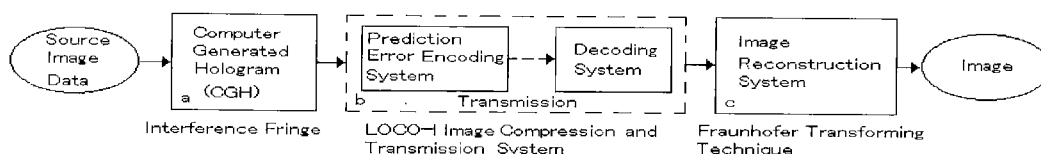


Fig. 1. Information compressed and transmitted and reconstructed system structure of CGH using LOCO-I image processing and Fraunhofer transforming technique.

W. Lohmann, we can understand, the size variation of CGH pixels is determined by amplitude function, the position variation of CGH pixels is determined by phase function. Thus in compression and transmission, if the pixel's size can be reduced (i.e., the limit value of CGH compressed can't be exceeded), and the pixel's position can be restored after CGH compressed, the image of CGH can be effectively compressed and transmitted and reconstructed.

On the other hand, in <sup>(1)</sup>, our experiment results have proved that the phase information of CGH is more important than the amplitude information of CGH. The amplitude information variation of CGH pixels only influences the image intensity, but the original information distribution of CGH isn't distorted. However, if the phase information of CGH pixels is varied, it will disturb the information distribution of CGH. Thus, we must choice an encoding algorithm that it will only compress the amplitude information of CGH pixels, but the phase information of CGH pixels will be lightly reduced (or it is said that the image of the processed CGH can be reconstructed by Fraunhofer transforming algorithm). Through experiments, we have found that LOCO-I image encoding algorithm can satisfy these requirements. To adapt LOCO-I algorithm model, the compression ratio of CGH can be improved, and it can achieve the near-lossless amplitude and phase information to compress the redundancy information contained in the original CGH. And the information of processed CGH is less influenced in compression and transmission and reconstruction.

The system structure of ICTRS and the method of processing CGH are presented in this paper. The algorithm principle of CGH is described in Sect.2. LOCO-I encoding algorithm model is described in Sect.3. The image-reconstructed algorithm of CGH is described in Sect.4. The experiment analyses, discussion and the conclusion are respectively described in Sect.5 and 6.

## 2. Computer Generated Hologram

According to the theory of E. N. Leith and J. Upatnieks <sup>(6)(7)</sup> in off-axis reference beam holograms, we have generated an on-axis reference beam hologram of 9 points with a computer. That is, the amplitude and phase transmittance of a hologram recorded under ideal conditions is proportional to

$$\begin{aligned} I(x, y) &= [r(x, y) + a(x, y)] [r(x, y) + a(x, y)]^* \\ &= |R(x, y) \exp[j\phi(x, y)] \\ &\quad + A(x, y) \exp[j\psi(x, y)]|^2 \end{aligned}$$

Table 1. Experiment data of CGH about 9 object points.

wave-length( $\lambda$ )	0.6328 $\mu$ m
sampling-points	11
$L_x \times L_y$	512 $\times$ 512
pixel <sub>x</sub> $\times$ pixel <sub>y</sub>	0.025 $\times$ 0.025mm <sup>2</sup>

$$\begin{aligned} &= R(x, y)^2 + A(x, y)^2 \\ &\quad + 2R(x, y)A(x, y)\cos[\phi(x, y) \\ &\quad - \psi(x, y)]. \dots\dots\dots (1) \end{aligned}$$

In Eq.(1),  $r(x, y) = R(x, y) \exp[j\phi(x, y)]$  represents the tilted reference wave function and  $a(x, y) = A(x, y) \exp[j\psi(x, y)]$  is the object wave function.  $I(x, y)$  is the resulting intensity variation of the interference pattern between the two waves. In experiment we have chosen that the positions of the reference beam  $r(x, y, z)$  and the object wave  $a(x, y, z)$  respectively are  $r(0, 0, 1500(\text{mm}))$  and  $a(0, 0, 150(\text{mm}))$ .

In terms of Eq.(1), we have made a CGH of 9 points and its histograms with a computer, and Fraunhofer transform technique has been adapted to reconstruct the original object (i.e., 9 points) as shown in Table 1 and Fig.7, 10 and 12.

## 3. LOCO-I Image Processing Model

LOCO-I is a lossless compression algorithm for continuous-tone images that combine the simplicity of Huffman coding with the compression potential of context models. The algorithm uses a non-linear predictor with rudimentary edge detecting capability, and is based on a simple fixed context model, determined by quantized gradients. A small number of free statistical parameters can be used to approach the capability of the more complex universal context modeling techniques for capturing high-order dependencies, without context dilution. The model is tuned for efficient performance in conjunction with a collection of Huffman codes, which is realized with an adaptive, symbol-wise, Golomb-Rice code. In one pass, LOCO-I attains compression ratios similar or superior to those obtained with state-of-the-art schemes based on arithmetic coding and without recourse to the higher complexity arithmetic coders.

LOCO-I follows a more traditional predictor-modeler-coder structure, in the use of an extremely simple explicit formula for Golomb-Rice parameter estimation and in the use of an embedded alphabet extension to reduce code redundancy. And the prediction modeling units are based on the causal template depicted, where  $x$  denotes the current pixel, and a, b, c and d are neigh-

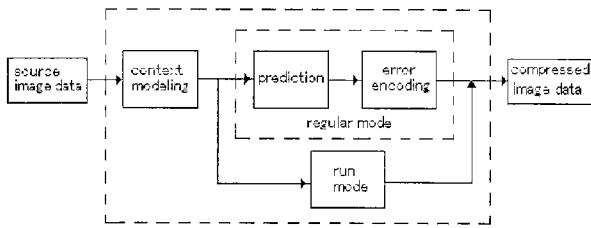


Fig. 2. Lossless encoder simplified diagram.

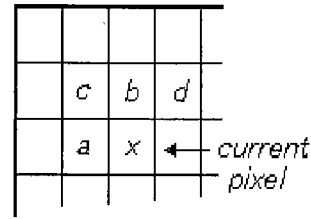


Fig. 3. Causal template used for context modeling and prediction.

boring pixels in the relative positions as shown in Fig.3. The dependence of a, b, c and d on the time index  $i$  has been deleted from the notation for simplicity.

In a context model scheme, reducing the number of parameters is a key objective. In a sequential formulation, the goal is to avoid the context dilution, while in a two-pass scheme LOCO-I can be expected to reduce unnecessary table overhead. The total number of parameters in the model depends on the number of free parameters defining the coding distribution at each context and on the number of contexts. In fact, LOCO-I has been considered by the ISO/ITU committee as a replacement for the current lossless standard in low-complexity applications <sup>(2)~(5)</sup>.

**3.1 Coding Principles of LOCO-I Algorithm Model** In LOCO-I, a source image is input to the encoder sample after sample in a pre-defined scan pattern, and lossless image compression is formulated as an inductive inference problem as follows. When coding the current sample, after having scanned past data, inferences can be made on the value of this sample by assigning a conditional probability  $\rho$  for the value of the current image sample, conditioned on previously received samples. This inference method is called modeling. The minimum average code length contribution of the current sample is  $-\log_2(\rho)$ . For near-lossless image compression this principle is modified to use reconstructed values of the preceding samples (instead of the original values) as conditioning data. During the encoding process, shorter codes are assigned to more probable events. The decoder can reconstruct the conditional probability used to encode the current samples, since it depends only on already decoded data <sup>(2)~(5)</sup>.

### 3.2 Encoding Process Steps

**3.2.1 Context Modeling** The encoding process steps of LOCO-I are described in Fig.2. In this international standard, the modeling approach used is based on the notion of 'context'. In context modeling, each sample value is conditioned on a small number of neighboring samples. The context modeling procedure determines a probability distribution used to encode the current sample, whose position,  $x$ , is shown in Fig.3. The context is determined from four neighborhood reconstructed samples at positions a, b, c, and d of the same component, as shown in Fig.3. From the values of the reconstructed samples at a, b, c, and d, the context first determines if the information in the sample  $x$  should be encoded in the regular or run mode <sup>(5)</sup>:

(1) The regular mode is selected when the context estimates samples are not very likely to be identical (for

lossless coding) or nearly identical within the tolerances required (for near-lossless coding).

(2) The run mode is selected when the context estimates that successive samples are very likely to be either identical (for lossless coding) or nearly identical within the tolerances required (for near-lossless coding).

**3.2.2 Regular Mode(include: Prediction and Error Encoding)** In the regular mode, the context determination procedure is followed by a prediction procedure. The predictor combines the reconstructed values of the three neighborhood samples at positions a, b, and c to form a prediction of the sample at position  $x$  as shown in Fig.3. The prediction error is computed as the difference between the actual sample value at position  $x$  and its predicted value. This prediction error is then corrected by a context-dependent term to compensate for systematic biases in prediction. In the case of near-lossless coding, the prediction error is then quantized.

The corrected prediction error (further quantized for near-lossless coding) is then encoded using a procedure derived from Golomb coding. The Golomb coding procedures specified in this International Standard depend on the context determined by the values of the samples at positions a, b, c, and d as well as prediction errors previously encoded for the same context <sup>(4)(5)</sup>.

**3.2.3 Run Mode** If the reconstructed values of the samples at a, b, c and d are identical for lossless coding, or the differences between them (the gradients, specified in <sup>(5)</sup>) are within the bounds set for near-lossless coding, the context modeling procedure selects the run mode and the encoding process skips the prediction and error encoding procedures. In run mode, the encoder looks, starting at  $x$ , for a sequence of consecutive samples with values identical (or within the bound specified for near-lossless coding) to the reconstructed value of the sample at a. This run is ended by a sample of a different value (or one which exceeds the bound specified for near-lossless coding), or by the end of the current line, whichever comes first. The length information, which also specifies one of the above two run-ending alternatives, is encoded using a procedure specified in <sup>(5)</sup>, which is extended from Golomb coding but has improved performance and adaptability.

**3.3 Decoding Process Steps** The encoding and decoding processes are approximately symmetrical. It is also said that the decoding processes are the encoding inverse processes. Therefore, the decoding process is not repeatedly described in this section. The detail of the decoding process is in <sup>(4)(5)</sup>.

4. Image Reconstructed of CGH with Fraunhofer Transforming Technique

According to above theories in Sect.1, we can understand, the algorithm of CGH compressed and transmitted and reconstructed must satisfy two conditions. That is, both the variation of amplitude and the variation of phase can be controlled in a limit value respectively as CGH compressed. Thus there are two limit values when the pixels of CGH are reduced. The limit value of amplitude compressed can be easily found with experiments (i.e., to see Table 2 and Fig.12 ~ 14). However, the limit value of phase reduced can't be easily found out through experiments. Because there isn't a suitable method that can precisely determine the position variation of pixel. And the phase variation of compressed pixels is relatively less than the amplitude variation of compressed pixels. In addition, this processing method is a randomization. So it is more difficult to determine the position variation of CGH pixels.

Fortunately, we have found out a method that can resolve this problem. That is, Fraunhofer transforming technique is adapted to reconstruct the images of the original CGH and the processed CGH, and then to compare the positions of their information distribution with each other. Because Fraunhofer transforming technique is a plane wave reconstruction algorithm, applying it to calculate, the reconstructed image of CGH is a black/white information distribution. Thus the positions of information distribution can be easily recognized by human visual system (i.e., to see Fig.10, 11.). That is one of the reasons why Fraunhofer transforming technique is adapted in this system.

Therefore, in transforming algorithm, if the diffraction-pattern calculation can be further simplified and the restrictions can be more stringent than those used in the Fresnel approximations are adopted, in particular, it was seen earlier that in the region of Fresnel diffraction the observed field strength  $h(x_2, y_2)$  can be found from a Fourier transform of the product of the aperture distribution  $h(x_1, y_1)$  with a quadratic phase function  $\exp[j(k/2z)(x_1^2 + y_1^2)]$ . If in addition the stronger assumption is adopted,

$$z \gg \frac{k}{2}(x_1^2 + y_1^2)_{max} \dots \dots \dots (2)$$

then the quadratic phase factor is approximately unity over the entire aperture, and the observed field distribution can be found directly from a Fourier transform of the aperture distribution itself. Thus in the region of Fraunhofer diffraction

$$h(x_2, y_2) = \frac{\exp(jkz)}{j\lambda z} \exp\left[\frac{jk}{2z}(x_2^2 + y_2^2)\right] \int \int_{-\infty}^{+\infty} h(x_1, y_1) \exp\left[-\frac{jk}{z}(x_2x_1 + y_2y_1)\right] dx_1 dy_1 \dots (3)$$

Aside from the multiplicative factors preceding the integral, this expression is simply the Fourier transform

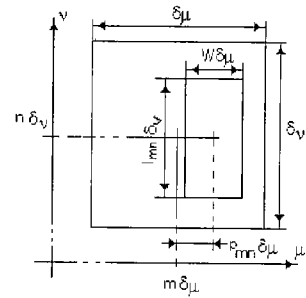


Fig. 4. Sampling unit.

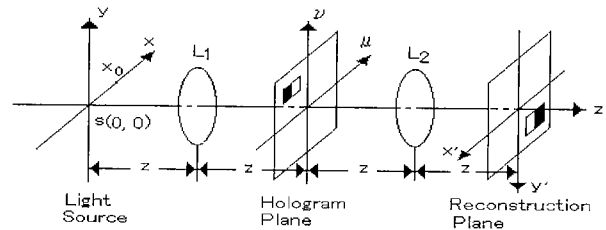


Fig. 5. Optical image reconstruction construction of CGH.

of the aperture distribution, evaluated at frequencies  $(\mu = x_2/\lambda z, \nu = y_2/\lambda z)$ . That is

$$h(x_2, y_2) = A \cdot F\{h(x_1, y_1)\} \Big|_{\substack{\mu=x_2/\lambda z \\ \nu=y_2/\lambda z}} = A \cdot H(\mu, \nu) \dots \dots \dots (4)$$

where  $A$  is defined as  $\frac{\exp(jkz)}{j\lambda z} \exp\left[\frac{jk}{2z}(x_2^2 + y_2^2)\right]$ . Therefore, if  $H(\mu, \nu)$  can be inverse Fourier transformed, the object wave of  $h(x_2, y_2)$  can be reconstructed by a computer.

In holography, the object's diffraction wave  $h(x_2, y_2)$  which is recorded on the hologram plane is Fraunhofer transform function of the object's amplitude distribution  $h(x_1, y_1)$  in the distance  $z$ . Therefore, it can be expressed by Eq.(4), where  $k$  is the wave number  $2\pi/\lambda$ . If the plane reference wave would be adapted to illuminate the hologram plane in Fig.5, then the original image of object can be reconstructed in the distance  $z$  <sup>(8)(9)</sup>. Therefore, according to holographic theory <sup>(6)(7)</sup>, every sampling unit function of hologram plane can be written by

$$rect\left[\frac{\mu - p_{mn}\delta_\mu}{W\delta_\mu}\right] rect\left[\frac{\nu}{l_{mn}\delta_\nu}\right] \dots \dots \dots (5)$$

the function  $rect(x)$  is given by

$$rect(x) = \begin{cases} 1 & \text{for } |x| \leq \frac{1}{2} \\ 0 & \text{otherwise.} \end{cases}$$

The equation of hologram plane function can be directly written by

$$H(\mu, \nu) = \sum_m \sum_n rect\left[\frac{\mu - (m + p_{mn})\delta_\mu}{W\delta_\mu}\right] \cdot rect\left[\frac{\nu - n\delta_\nu}{l_{mn}\delta_\nu}\right] \dots \dots \dots (6)$$

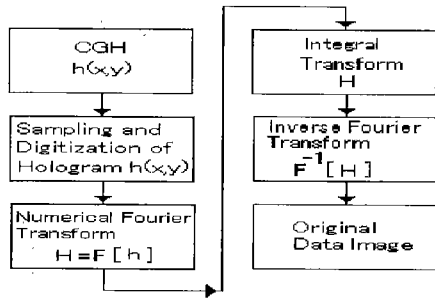


Fig. 6. Fraunhofer transform algorithm flow diagram.

As shown in Fig.4, 5, the rectangular aperture is drawn inside each cell in hologram plane, each aperture is determined by three parameters: its height  $l_{mn}$ , its width  $W$ , and its center with respect to the center of the cell  $p_{mn}$ .  $\delta_\mu$  and  $\delta_\nu$  are the sampling distances along the  $\mu$  and  $\nu$  coordinates. The index  $m, n$  indicates the relative location of the cell in the hologram plane.

If CGH is placed in the optical system of Fig.5, then the hologram is illuminated with a plane wave  $\exp[j2\pi x_0\mu]$  in  $x_0$ . Lens  $L_2$  performs the inverse Fourier transformation to produce the wavefront  $A(x, y) \exp[j\phi(x, y)]$  at the back focal plane of lens  $L_2$ . The wavefront  $h(x, y)$  at the back focal plane of lens  $L_2$  is

$$\begin{aligned}
 h(x, y) &= \int \int_{-\infty}^{+\infty} H(\mu, \nu) \\
 &\quad \cdot \exp[j2\pi x_0\mu] \exp[j2\pi(\mu x + \nu y)] d\mu d\nu \\
 &= \sum_m \sum_n l_{mn} W \delta_\mu \delta_\nu \text{sinc}[l_{mn} y \delta_\nu] \\
 &\quad \cdot \text{sinc}[W(x + x_0)\delta_\mu] \exp[j2\pi n y \delta_\nu] \\
 &\quad \cdot \exp[j2\pi(x + x_0)(m + p_{mn})\delta_\mu] \cdots \quad (7)
 \end{aligned}$$

In the reconstructed image plane, we can get the original object wave  $h(x, y)$ . If the illumination light source is on-axis (i.e.,  $x_0 = 0$ ), Eq.(7) can be more simplified as

$$\begin{aligned}
 h(x, y) &= \int \int_{-\infty}^{+\infty} H(\mu, \nu) \exp[j2\pi(\mu x + \nu y)] d\mu d\nu \\
 &= \sum_m \sum_n l_{mn} W \delta_\mu \delta_\nu \text{sinc}[l_{mn} y \delta_\nu] \\
 &\quad \cdot \text{sinc}[W x \delta_\mu] \exp[j2\pi n y \delta_\nu] \\
 &\quad \cdot \exp[j2\pi x(m + p_{mn})\delta_\mu] \cdots \cdots \cdots \quad (8)
 \end{aligned}$$

$$\begin{aligned}
 h(x, y) &= \sum_m \sum_n l_{mn} W \delta_\mu \delta_\nu \frac{\text{sin}[\pi l_{mn} y \delta_\nu]}{\pi l_{mn} y \delta_\nu} \\
 &\quad \cdot \frac{\text{sin}[\pi W x \delta_\mu]}{\pi W x \delta_\mu} \\
 &\quad \cdot \exp\{j2\pi[(m + p_{mn})x\delta_\mu + ny\delta_\nu]\} \quad (9)
 \end{aligned}$$

According to Eq.(9), if the parameters of  $p_{mn}$ ,  $l_{mn}$ ,  $W$  and the illumination source  $s(x_0, y_0)$  can be properly chosen, the object wave  $f(x, y) = A(x, y) \exp[j\phi(x, y)]$  of  $h(x, y)$  can be reconstructed by a computer.

Therefore, in terms of the above derivation, the complete numerical reconstruction is calculated procedure: (1) sampling and digitization of a CGH  $h(x, y)$ , (2) calculation of the digital Fourier transform  $H(\mu, \nu)$  from digitized hologram, (3) calculation of the product  $H(m, n)$  of Fourier transforming integral, (4) calculation of the inverse digital Fourier transform of  $H$  corresponding to the image  $O(x, y)$  of the original object as shown in Fig.6 (6)~(9).

## 5. Experiment Analyses and Discussion

### 5.1 Compression Efficiency and Distortion Measure

There are subjective criteria to decide if an image is distorted or not: the observation by the eye, and the comparison between the original image and the processed image. But it is not enough to determine objectively the quality of the image. That is why we must bring up the concept of *MSE* and *PSNR*.

According to the image processing theories, Eqs.(10), (11) and (12) of the compression ratio and the distortion measure can be written (10). *R*, *MSE* and *PSNR* of the processed CGH in this system can be precisely calculated. Their relationship curves can be drawn as shown in Fig.15 and 16.

$$R = \frac{S_c}{S_o} \cdots \cdots \cdots \quad (10)$$

Where *R* is the compression ratio,  $S_o$  is defined as the size of the original image data and  $S_c$  is the size of the compressed image data.

$$MSE = \frac{1}{512^2} \sum_{x=1}^{x=512} \sum_{y=1}^{y=512} [f(x, y) - \bar{f}(x, y)]^2 \quad (11)$$

$$PSNR = 10 \log_{10} \left[ \frac{x_p^2}{MSE} \right] (dB) \cdots \cdots \cdots \quad (12)$$

Where  $x, y$  are 1 ~ 512.  $f(x, y)$  is CGH's image function (or reconstructed image function of original CGH),  $\bar{f}(x, y)$  is the decompressed CGH's image function (or reconstructed image function of decompressed CGH),  $x_p$  is 255 (peak to peak value of the image data).

### 5.2 CGH Compressed, Decompressed and Compression Ratio

According to Eq.(10), the experiment data of compressed, decompressed and compression ratio (*R*%) of CGH can be calculated as shown in Table 2. The original CGH, compressed CGH, decompressed CGH and reconstructed image of CGH have been shown in Fig.7~11. The histograms of original and decompressed CGH have been shown in Fig. 12 ~ 14.

To analyze Fig.7~14, we can find that the information distribution shape of 9 points diffraction fringe isn't destroyed as comparing Fig.7 with Fig.9. And that the information distribution positions of both the reconstructed original image of CGH and the reconstructed image of processed CGH aren't varied as comparing Fig.10 with Fig.11. Moreover, as comparing Fig.12 with Fig.13, 14, we have found that the information field intensity distribution of CGH is reduced the dilution, and there is a little noise. But the information distribution

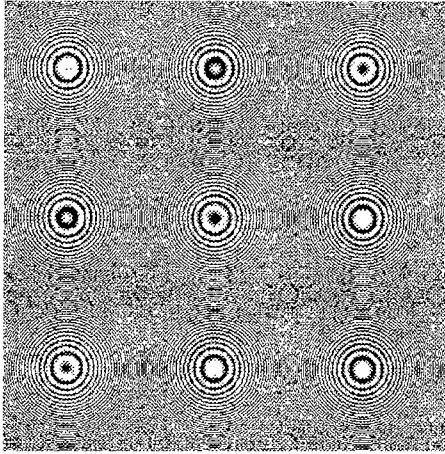


Fig. 7. Original CGH (size:  $7.11 \times 7.11inch^2$ ,  $512 \times 512pixel^2$ , 257kb, 8bpp/256).

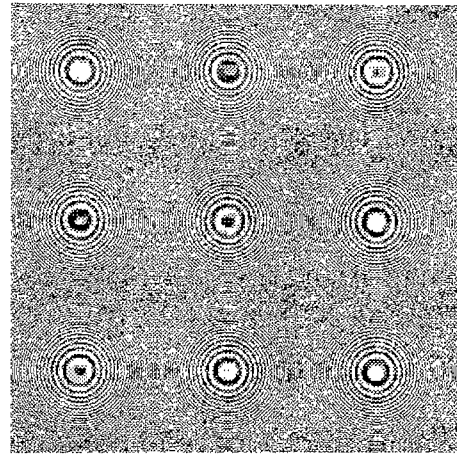


Fig. 9. Decompressed CGH (size:  $7.11 \times 7.11inch^2$ ,  $512 \times 512pixel^2$ , 257kb, 8bpp/256,  $e(N)=90$ ,  $R = 100\%$ ).

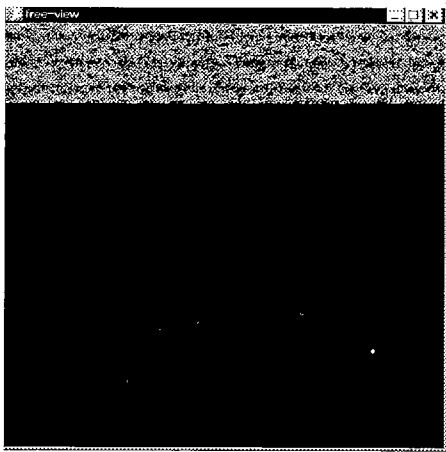


Fig. 8. Compressed CGH (size:  $7.11 \times 7.11inch^2$ ,  $512 \times 512pixel^2$ , 48kb, 8bpp/256,  $e(N)=90$ ,  $R = 18.78\%$ ).



Fig. 10. Reconstructed image of original CGH using Fraunhofer transforming technique (size:  $7.11 \times 7.11inch^2$ ,  $512 \times 512pixel^2$ , 257kb, 8bpp/256).

shape and position isn't varied and the image of the processed CGH can be reconstructed in limited value range. Therefore, we can evaluate that the reconstructed information distribution of the original and processed CGH is basically identical. In Fig.12, 13, 14, the histograms can be clearly seen about the frequency variation of processed CGH. In Sect.1 and Sect.4, the analyzed theories have effectively been verified by experiment images.

Table 2. Experiment data of compressed, decompressed and compressed ratio of CGH.

$e(N) = 10$	$CGH_{original}$	$CGH_{compressed}$	$CGH_{decompressed}$
Size	257kb	117kb	257kb
R(%)		45.4904	100
$e(N) = 30$	$CGH_{original}$	$CGH_{compressed}$	$CGH_{decompressed}$
Size	257kb	78kb	257kb
R(%)		30.212	100
$e(N) = 60$	$CGH_{original}$	$CGH_{compressed}$	$CGH_{decompressed}$
Size	257kb	58kb	257kb
R(%)		22.369	100
$e(N) = 70$	$CGH_{original}$	$CGH_{compressed}$	$CGH_{decompressed}$
Size	257kb	53kb	257kb
R(%)		20.4162	100
$e(N) = 90$	$CGH_{original}$	$CGH_{compressed}$	$CGH_{decompressed}$
Size	257kb	48kb	257kb
R(%)		18.7806	100

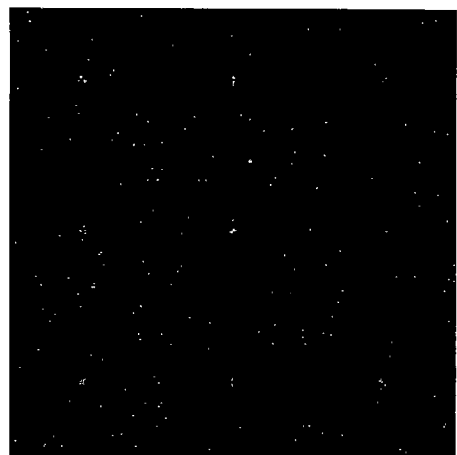


Fig. 11. Reconstructed image of decompressed CGH using Fraunhofer transforming technique (size:  $7.11 \times 7.11inch^2$ ,  $512 \times 512pixel^2$ , 257kb,  $e(N)=90$ ), 8bpp/256.

### 5.3 CGH Transmitted Error and Reconstructed Image Quality

In Table 3, the relation-

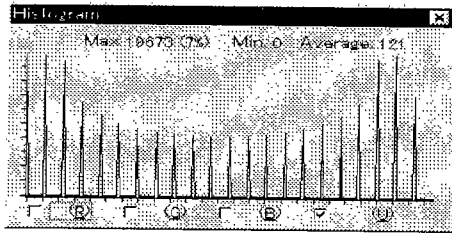


Fig. 12. Histogram of original CGH.

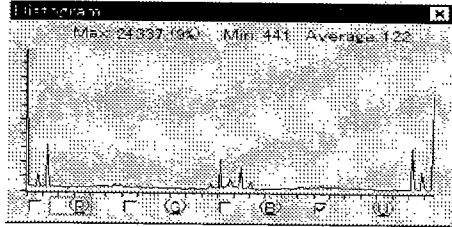


Fig. 13. Histogram of decompressed CGH ( $e(N)=60$ ).

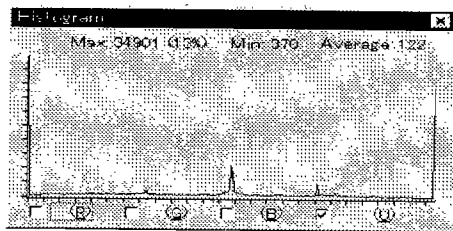


Fig. 14. Histogram of decompressed CGH ( $e(N)=90$ ).

Table 3. Relationship data about  $R\%$ ,  $MSE$  and  $PSNR$  under comparing the original CGH with the decompressed CGH.

$e(N)$	10	20	30	40	50
$R(\%)$	45.4904	35.566	30.212	25.815	23.872
$MSE$	36.26925	133.124	283.567	481.522	728.564
$PSNR$	32.5354	26.888	23.604	21.305	19.506
$e(N)$	60	70	80	90	95
$R(\%)$	22.369	20.4162	19.607	18.7806	18.159
$MSE$	1021.692	1365.6864	1686.982	2068.1426	2394.260
$PSNR$	18.038	16.7773	15.859	14.9749	14.339

ship data about  $R(\%)$ ,  $MSE$  and  $PSNR$  under comparing the original CGH with the decompressed CGH are described.  $e(N)$  is defined as the parameter range for lossless coding  $N = 0$ ,  $range = maxval + 1$ , for near-lossless coding  $N > 0$ ,  $range = \lfloor \frac{maxval + 2 * N}{2 * N + 1} \rfloor + 1$  in LOCO-I<sup>(5)</sup>.† The relationship curves are shown in Fig. 15.

To analyze Fig. 15, the more precision relationship of this system can be found from  $R$ ,  $MSE$  and  $PSNR$  of CGH compressed and reconstructed. The "lossless" or "near-lossless" compression algorithm model can be criticized by these parameter data. In terms of Fig. 15, we can understand that  $MSE$  is directly proportional to  $R(\%)$ .  $PSNR$  is inversely proportional to  $R(\%)$ .

In Table 4, the relationship data about  $R(\%)$ ,  $MSE$  and  $PSNR$  under comparing the reconstructed image of original CGH with the reconstructed image of decompressed CGH are described. The relationship curves are

†e.g., nlocoe -e(N) CGH.pgm; Compresses CGH.pgm in LI mode with loss=N, i.e., maximal allowed error +/-N.

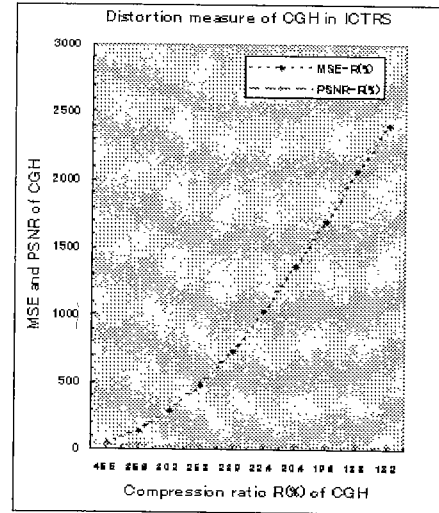


Fig. 15. Relationship curves about  $MSE$ ,  $PSNR$  and  $R(\%)$  in Comparing the original CGH with the decompressed CGH in ICTRS.

Table 4. Relationship data about  $R(\%)$ ,  $MSE$  and  $PSNR$  under comparing the reconstructed images of original CGH with the reconstructed images of decompressed CGH.

$e(N)$	10	20	30	40	50
$R(\%)$	45.4904	35.566	30.212	25.815	23.872
$MSE$	0.3867	1.07343	2.13498	3.4446	5.0774
$PSNR$	52.2571	47.8231	44.8369	42.7594	41.0744
$e(N)$	60	70	80	90	95
$R(\%)$	22.369	20.4162	19.607	18.7806	18.159
$MSE$	7.5525	9.29696	10.8894	12.35302	13.9103
$PSNR$	39.3499	38.4474	37.7608	37.21307	36.6974

shown in Fig. 16. The quality of reconstructed images of CGH is inversely proportional to  $R(\%)$ .

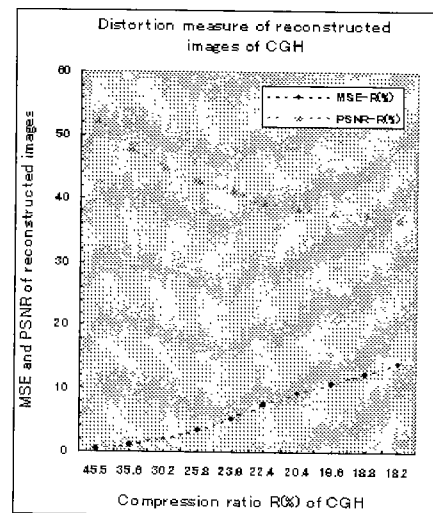


Fig. 16. Relationship curves of  $R(\%)$ ,  $MSE$  and  $PSNR$  in comparing the reconstructed images of original CGH with the reconstructed images of decompressed CGH.

## 6. Conclusion

In this paper, the information compressed and transmitted and reconstructed software system (ICTRS) of

CGH has been designed and established. This system can reconstruct and display the bigger images (i.e.,  $7.11 \times 7.11 \text{ inch}^2$ ), whose compression ratio can be achieved to 1:5, and the original image of CGH can be effectively reconstructed by ICTRS. The experiment results have effectively verified the theory discussed in Sect.1, that is the amplitude information of CGH has been reduced and the information of compressed phase can be effectively restored. To compare the reconstructed image (i.e., Fig.10) of original CGH with the one (i.e., Fig.11) of processed CGH, the processed CGH can be effectively reconstructed by ICTRS.

In processing CGH, if the lost information of CGH exceeds certain limited value, its original information distribution will be varied (i.e., the limit values of compressed CGH must be controlled in  $0 \leq \epsilon(N) \leq 90$  and  $18.7806\% \leq R(\%) \leq 100\%$  in Table 3, 4). And the reconstructed image of processed CGH can be directly observed by human visual system. The intensity  $I(x, y)$  of the elements distribution of CGH has been decreased by the amplitude information compressed. But the original information distribution of CGH isn't distorted. The experiment results have verified that LOCO-I image encoding algorithm can satisfy the conditions of CGH reconstructed (i.e., the variation limit values of the amplitude and phase of CGH pixels compressed).

Potential applications of this system include the instrument complex using facsimile equipment for digital hologram input and recording<sup>(14)</sup>, and the radar-guided system. In the future, perhaps it may be applied in the holography movie system<sup>(15)</sup> and the coding techniques for holographic data storage systems<sup>(16)</sup>.

In our experiments, we have chosen the symmetrical and the asymmetrical image of CGH to do the experiments. However, in order to explain simply the image quality of CGH compressed and transmitted and reconstructed, we have analyzed the symmetrical one. Anyway, the experiment results have told us: we can use only computer software to complete effectively the total process of CGH compressed and transmitted and reconstructed.

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